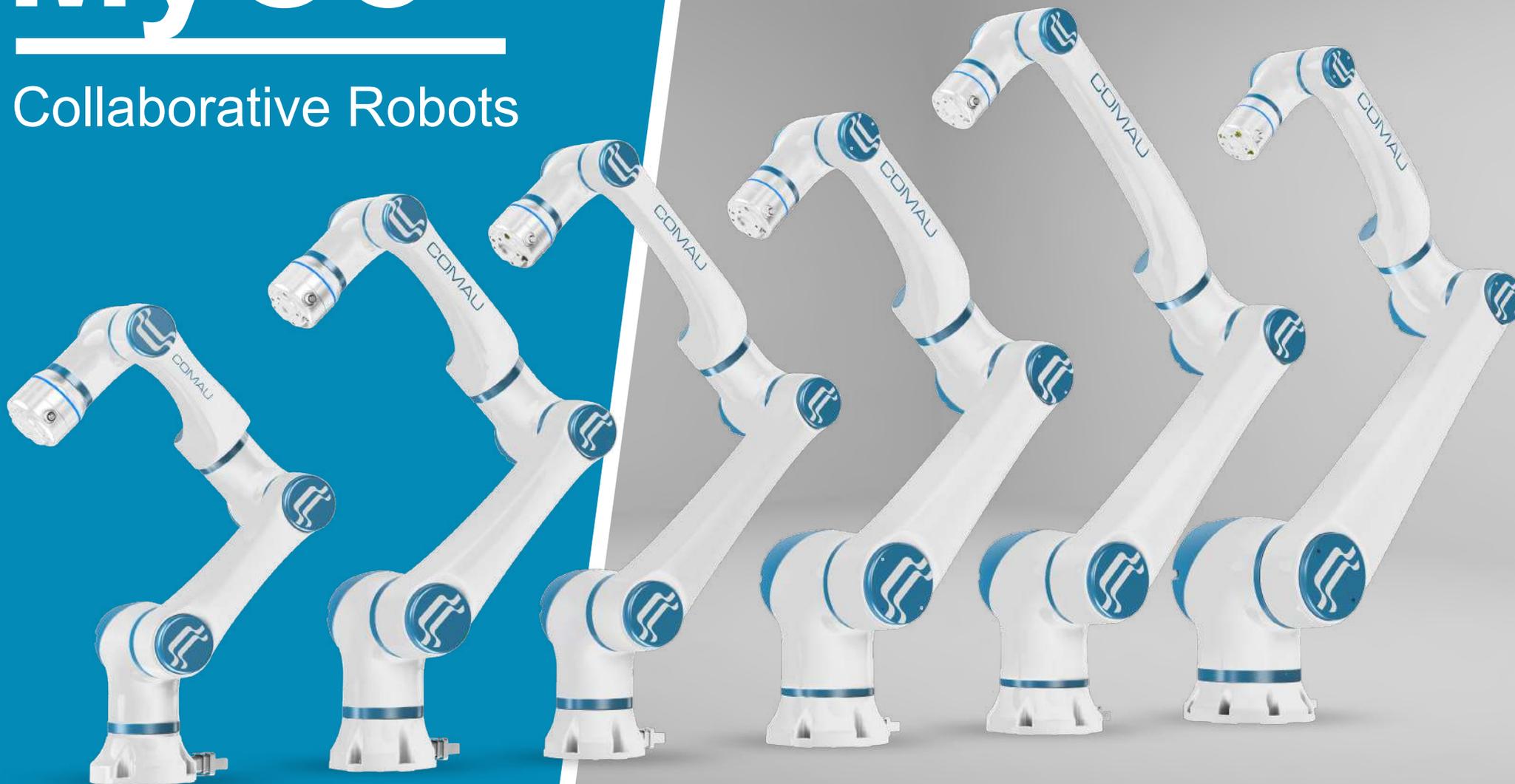


# MyCo

Collaborative Robots



## Smarter Collaboration

### Seamless integration and programming

The MyCo family of cobots is designed for **quick installation**, **easy programming**, and **rapid redeployment** to support faster lead times and reduce integration complexity.

Combining collaborative safety features with ergonomic benefits, MyCo enables humans and robots to work side-by-side, improving employee well-being, optimizing floorspace, and supporting safer, more inclusive operations.

With six lightweight models (**3 kg to 15 kg payloads**), Comau's new collaborative robot family delivers a precise, reliable and cost-effective automation solution for companies of all sizes.

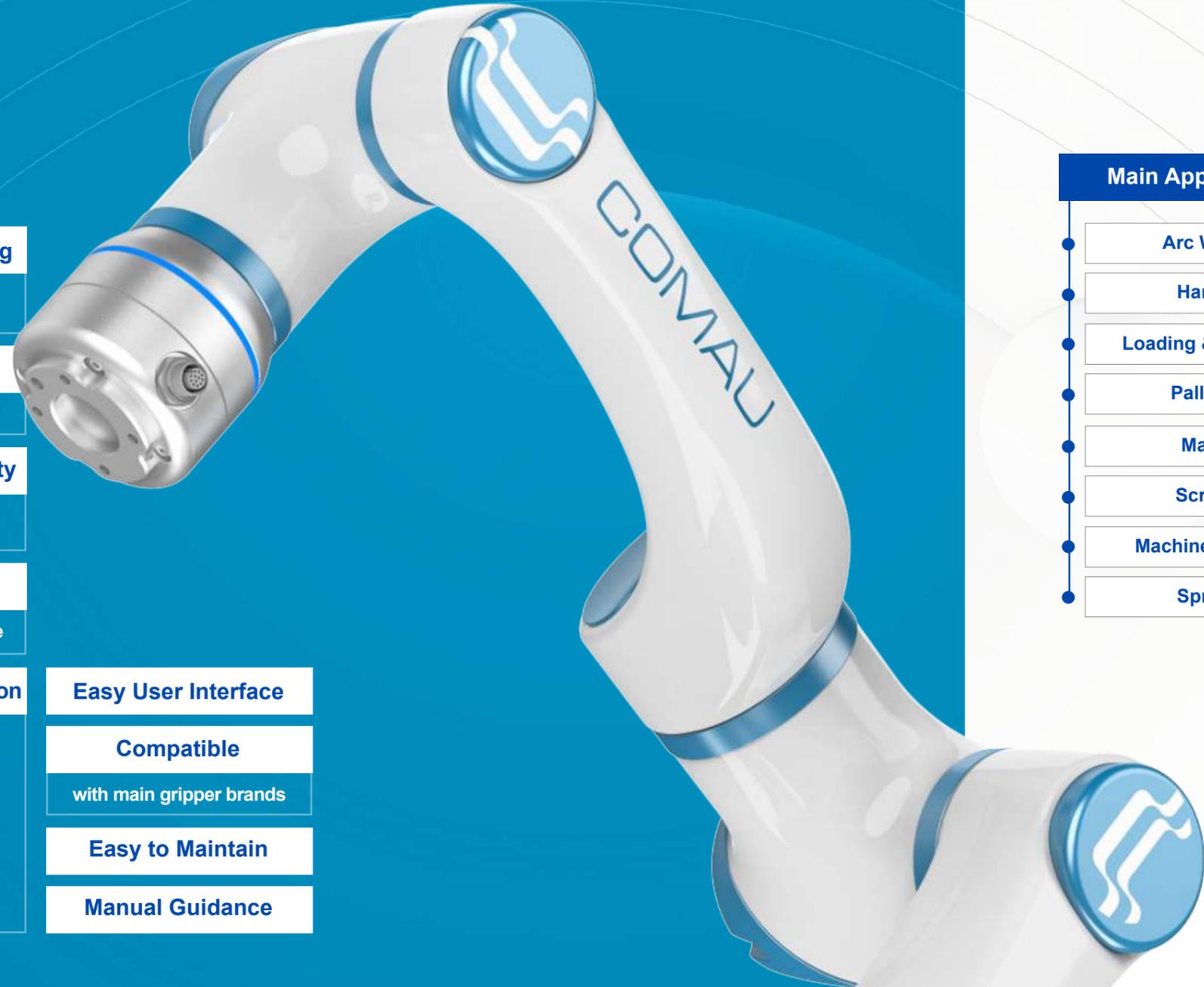


Technical Info  
MyCo Family

| Model                           | MyCo-3-0.59  | MyCo-3.5-0.95  | MyCo-5-0.80  | MyCo-8-1.30  | MyCo-10-1.00   | MyCo-15-1.30   |
|---------------------------------|--|--|--|--|--|--|
| Weight                          | 18kg   | 26kg   | 25kg   | 45kg   | 43kg   | 60kg   |
| Payload                         | 3kg  | 3.5kg  | 5kg  | 8kg  | 10kg   | 15kg   |
| Reach                           | 590mm  | 950mm  | 800mm  | 1300mm   | 1000mm   | 1300mm   |
| Power Consumption               | "100W<br>Typical Application"  | "180W<br>Typical Application"                          | "180W<br>Typical Application"                          | "350W<br>Typical Application"                          | "350W<br>Typical Application"                          | "600W<br>Typical Application"                          |
| Joint Range                     | "J1, J4, J6 ±360°<br>J2 ±135°<br>J3 ±150°<br>J5 ±147°"                   | "J1, J4, J6 ±360°<br>J2 ±135°<br>J3 ±153°<br>J5 ±180°" |
| Joint Speed                     | "J1-J4 180°/s<br>J5-J6 200°/s"   | "J1-J4 180°/s<br>J5-J6 200°/s"                         | "J1-J4 180°/s<br>J5-J6 200°/s"                         | "J1-J2 100°/s<br>J3-J4 150°/s<br>J5-J6 180°/s"         | "J1-J2 100°/s<br>J3-J4 150°/s<br>J5-J6 180°/s"         | "J1-J2 80°/s<br>J3-J4 120°/s<br>J5-J6 150°/s"          |
| Tool Speed                      | 2m/s   | 3m/s   | 3m/s   | 2.5m/s   | 2m/s   | 2m/s   |
| Repeatability                   | ±0.02mm  | ±0.02mm  | ±0.02mm  | ±0.03mm  | ±0.03mm  | ±0.05mm  |
| Degree of Freedom               | 6  |  |  |  |  |  |
| Dust and Water Protection Class | IP54 (IP66 optional)   |  |  |  |  |  |
| UL94 Classification             | V0   |  |  |  |  |  |
| Mounting Position               | Floor / Ceiling / Inclined Plane / Wall                                  |  |  |  |  |  |
| End I/O Port                    | Digital input: 3, Digital output: 3, Analog input: 2                     |  |  |  |  |  |
| Control box I/O port            | Digital input: 16, Digital output: 16, Analog input: 2, Analog output: 2 |  |  |  |  |  |
| I/O Source                      | 24V 2A   |  |  |  |  |  |
| Communication                   | TCP/IP, ModbusTCP, Profinet (Optional), Ethernet/IP (Optional)           |  |  |  |  |  |
| Programming                     | Graphical Programming, Remote calling interface                          |  |  |  |  |  |
| Collaborative Operation         | 10 advanced security configuration functions                             |  |  |  |  |  |
| Main Material                   | Aluminium Alloy  |  |  |  |  |  |
| Working Temperature             | 0-50°C   |  |  |  |  |  |
| Power Input                     | 100-240V AC, 50-60Hz   |  |  |  |  |  |
| Cable                           | Cable to control box: 5m, Cable to teach pendant: 5m                     |  |  |  |  |  |

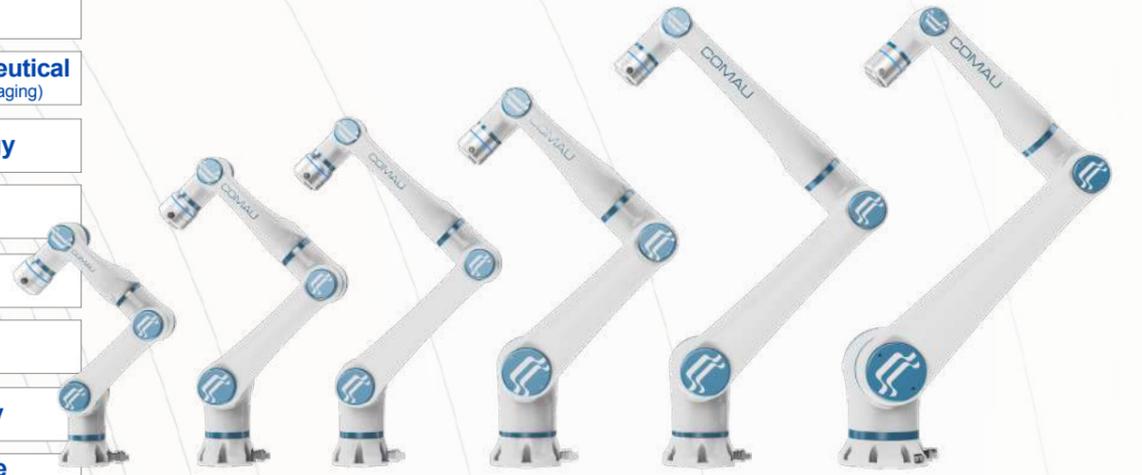
## Main Features

|   |  |                            |
|---|--|----------------------------|
| <b>Variety of Models</b>                    |  |                            |
| <b>Fully integrated with ROS/ROS2</b>       |  |                            |
| for advanced robotics in collaboration mode |  |                            |
| <b>Low Weight</b>                           | <b>Best Joint Positioning</b>  |                            |
|   | for applications and cycle times   |                            |
| <b>Easy Deployment</b>                      | <b>Ease of Equipment</b>   |                            |
|   | with external dressings  |                            |
| <b>Easy Installation</b>                    | <b>Excellent Repeatability</b>   |                            |
|   | for precise applications such as Arc Welding   |                            |
| <b>Easy to Program</b>                      | <b>High Speed</b>  |                            |
|   | in non collaborative mode  |                            |
| <b>High Precision</b>                       |  | <b>Easy User Interface</b> |
| <b>High Flexibility</b>                     |  | <b>Compatible</b>          |
|   |  | with main gripper brands   |
| <b>Modular Design</b>                       | <b>Force Control Integration</b>   | <b>Easy to Maintain</b>    |
|   | <ul style="list-style-type: none"> <li>Constant force control for perfect trajectory</li> <li>Fast programming</li> <li>Soft control with smooth free-drive teaching</li> <li>Cartesian manual guidance</li> </ul> | <b>Manual Guidance</b>     |
| <b>High Protection</b>                      |  |                            |
| against dust and water                      |  |                            |
| <b>UL94V0</b>                               |  |                            |
| <b>Internal Cabling</b>                     |  |                            |



## Main Industries and Applications MyCo Collaborative Robots

| Main Applications   | Main Industries  |
|---------------------|--|
| Arc Welding         | Automotive   |
| Handling            | Healthcare & Pharmaceutical<br><small>(warehouse or secondary packaging)</small> |
| Loading & Unloading | Renewable Energy   |
| Palletizing         | Education  |
| Marking             | Metalworking   |
| Screwing            | Naval  |
| Machine Finishing   | Railway Industry   |
| Spraying            | Food & Beverage<br><small>(warehouse or secondary packaging)</small>             |



## When is the Collaborative Robot needed?

|   |  |   |  |
|---|--|---|--|
| <p>When available space in the plant is limited</p> | <p>When you need to make man and robot cooperate</p> | <p>When the process and volume requirements can be met at the same speed as an operator</p> | <p>When you need flexibility to automate a wide variety of processes</p> |
|---|--|---|--|

## Why choose Comau's Cobot? Our Value Proposition

### Technical support and after sales

- Direct contact with our worldwide customer
- No language barriers

### 50+ years of experience as System Integrators

- Vision Systems
- IoT
- Industry 4.0 and 5.0
- Partnerships with the main end-effectors brands
- Standard Cell solutions
- Process and Simulation Skills

### Realistic industrial vision

- The Collaborative Robot is an industrial object: it takes expertise and training
- Both the application and the robot itself must be collaborative



## Why choose Comau's Cobot? Our Value Proposition

### Complete portfolio

- Comau has a full portfolio of industrial and collaborative robots - we can help you choose the right robot for the right application
- Applications and regulations expertise
- Experience in robot selection, setup and cycle time calculation

### Complete training

- Remote Training
- In-person Training
- Cycle Simulation in our plant
- Webinars
- Product Presentations



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**Made in Comau**